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superimposing same lines and rectify images ¿ [Search]   Advanced Search
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The **"AND"** operator is unnecessary -- we include all search terms by default. [details]

Web Results **1 - 10** of about **527** for <u>superimposing</u> <u>same</u> <u>lines</u> and <u>rectify</u> <u>images</u> and <u>disparity</u> <u>map</u>. (0.1€

[PDF] <u>Applications of a direct algorithm for the **rectification** of ...</u>
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from determining the epipolar geometry to calculating the **disparity map** over ... location in
both **images**, usually on the **same** horizontal **line** of pixels, ...
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<u>GlauCAD: Workplan</u>
Once the **images** have been rectified, a dense **disparity map** will be ... ensures that
matches will lie in the **same** order along corresponding epipolar **lines**. ...
www.msr.uni-bremen.de/glaucad/workplan.html - 33k - <u>Cached</u> - <u>Similar pages</u>

[PDF] <u>A New Approach for Stereo Matching in Autonomous Mobile Robot ...</u>
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images representing the **same** point of the scene; this. process is called **disparity**
matching. ... The main idea of our approach is to obtain a **disparity map** ...
www.ijcai.org/papers07/Papers/IJCAI07-339.pdf - <u>Similar pages</u>

[PDF] <u>Comparison of Stereo Matching Algorithms for Mobile Robots</u>
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pixel of the right **image** on that **same line**. The **image rectification** causes a ... The stereo
matching algorithm starts by **superimposing** two regions, one ...
robotics.ee.uwa.edu.au/theses/2005-Stereo-Kuhl.pdf - <u>Similar pages</u>

[PDF] <u>A Photorealistic Predictive Display</u>
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plays have been suggested, these displays **superimpose** simple (Noyes & Sheri- ... A
rectified camera **image**, its **disparity map**, the initial triangulation, ...
www.mitpressjournals.org/doi/abs/10.1162/105474604774048216 - <u>Similar pages</u>

<u>EP1235439 Sharp european software patent - Method and apparatus ...</u>
Image rectification is a. process for eliminating vertical **disparity** ... **lines** in the
transformed **images** will be horizontal and have the **same** y offset. ...
gauss.ffii.org/PatentView/EP1235439 - 109k - <u>Cached</u> - <u>Similar pages</u>

[PDF] <u>On the Importance of Being Asymmetric in Stereopsis—Or Why We ...</u>
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of **lines**.) By zero **disparity**, people usually mean that. when **superimposing** the left **image**
plane onto the right. **image** plane, points coincide. ...
www.springerlink.com/index/L3550J8087428W45.pdf - <u>Similar pages</u>

[PS] <u>GENERATING SEAMLESS STEREO MOSAICS FROM AERIAL VIDEO</u>
File Format: Adobe PostScript - <u>View as Text</u>
2) **Image rectification**: Data amount to be processed 2×2×M×L pixels (**same** as the next ...
frame for every point in one of the mosaics with a fixed **disparity**. ...
www-cs.ccny.cuny.edu/~zhu/ZhuASPRS01.ps - <u>Similar pages</u>

<u>WASHINGTON UNIVERSITY</u>
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How points in one **image map** to corresponding epipolar **lines** in the other is ... the **same**

over all scanlines, the **disparity** d for the true match should have ...
seas.wustl.edu/Research/FileDownload.asp?257 - Similar pages

[PDF] Underwater 3D SLAM through Entropy Minimization
File Format: PDF/Adobe Acrobat - View as HTML
dense **disparity image** and occlusion **map**. The **disparity image** ... The **same** holds for ...
from **superimposing** all the point clouds with respect to the ...
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#1   ((rectify images<in>metadata) <and> (superimposing
        lines<in>metadata))<and> (disparity map<in>metadata)

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		DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=OR	
☐	L13	disparity same map$5 and 3D same surface and unlikely and likely and multiresolution	0
☐	L12	L11 and (trace or tracing) same voxel$1 same seed	1
☐	L11	calibrat$3 and uncalibrat$3 and superimpos$3 and r(ectified or rectify) same image$1 same line$1 and voxel and error and likelihood and seed	134
☐	L10	382/294.ccls.	770
☐	L9	382/226.ccls.	286
☐	L8	382/154.ccls.	1666
☐	L7	345/427.ccls.	809
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